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AREVA

***WIND FARM***  
***Flexible AC Transmission Systems***

***WIND ENERGY AND GRID INTEGRATION***

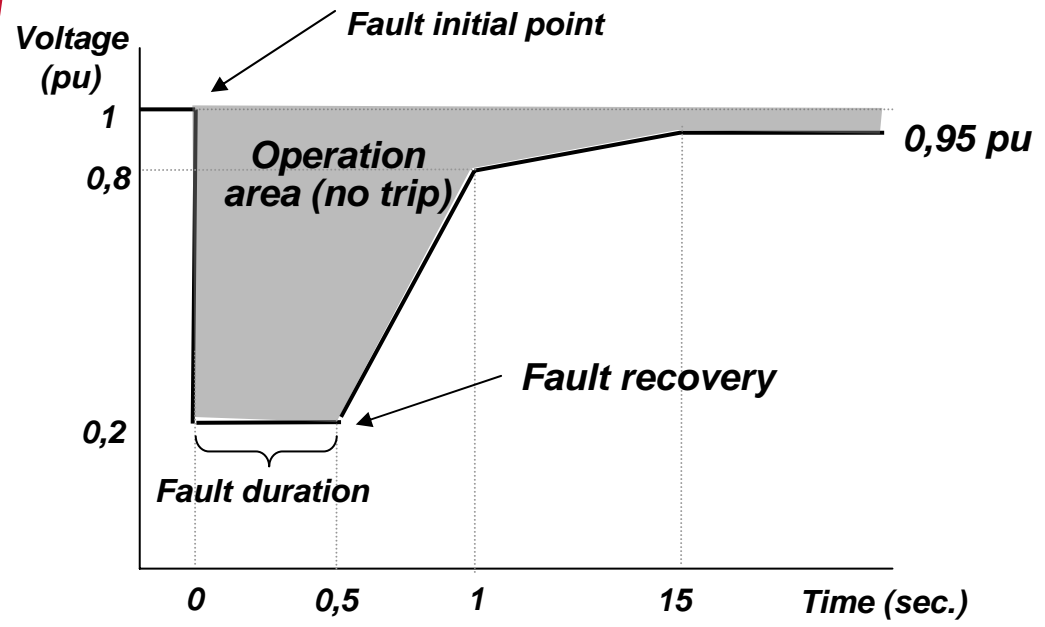
***Madrid 24-25 January 2006***

***Jacques COURAULT***

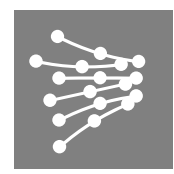
## Assumption:

*Wind farm is with Fixed Speed Induction Generator (FSIG)*

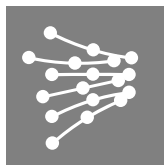
- ▶ 1/ Wind farm operation **WITHOUT** compensation:
  - ◆ Single line diagram / main assumptions
  - ◆ Physical aspects - System behaviour,
  - ◆ Main factors on system behaviour,
  - ◆ Simulations.
- ▶ 2/ Wind farm operation **WITH DYNAMIC** compensation:
  - ◆ Single line diagram,
  - ◆ Design,
  - ◆ Simulations,
- ▶ 3/ Conclusion & cost mitigation



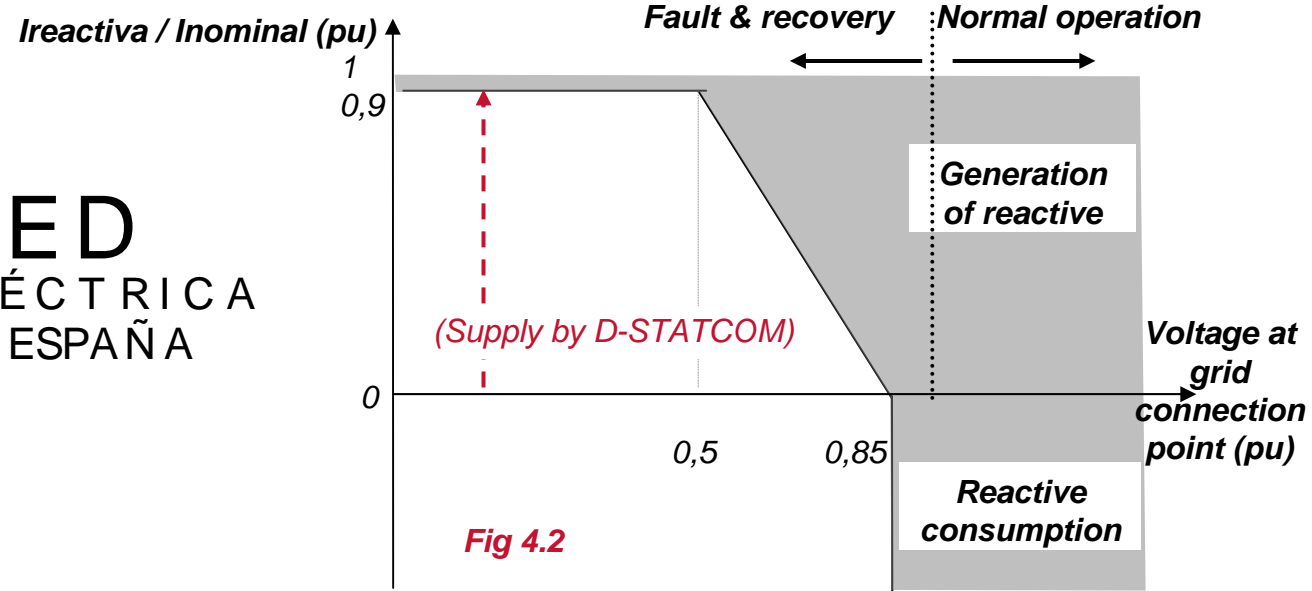
**Fig 4.1**



**RED**  
ELÉCTRICA  
DE ESPAÑA



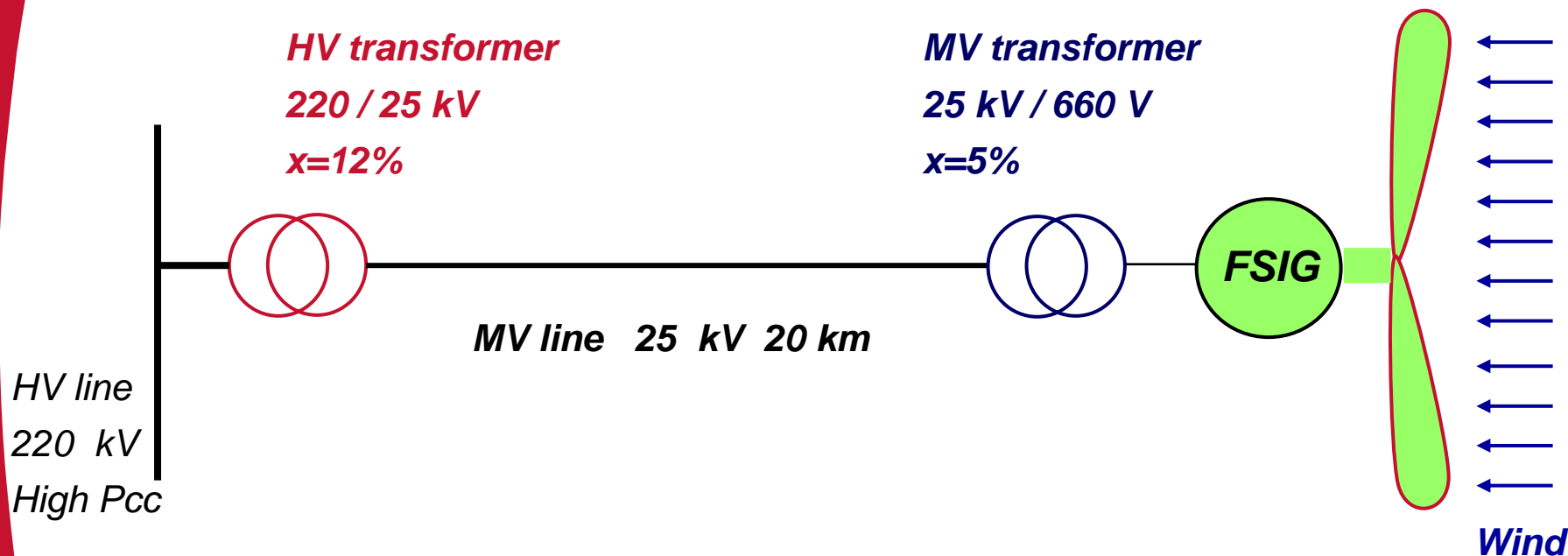
**RED**  
ELÉCTRICA  
DE ESPAÑA



**Fig 4.2**

# ***1 – WIND FARM OPERATION WITHOUT COMPENSATION***

# WITHOUT compensation / Single line diagram



► **Assumptions:**

- ◆ induction, fixed speed generator,
- ◆ in principal, network arrangement,
- ◆ wind-farm power: from 30 to 50 MVA (approach in pu)

# WITHOUT COMPENSATION PHYSICAL ASPECTS

## ▶ Fault phase (phase 1)

### ◆ active energy / mechanical behaviour:

- During Fault  $P_{mech} = \text{Constant}$ ,
- Mechanical acceleration according to Inertia,
- Slip of induction generator is increasing,
- Torque at induction generator is decreasing (square of the voltage).

### ◆ Reactive current injection

- Generator Voltage > Network Voltage,
- Short time duration  $\sim T$ 's (opened rotor time constant).

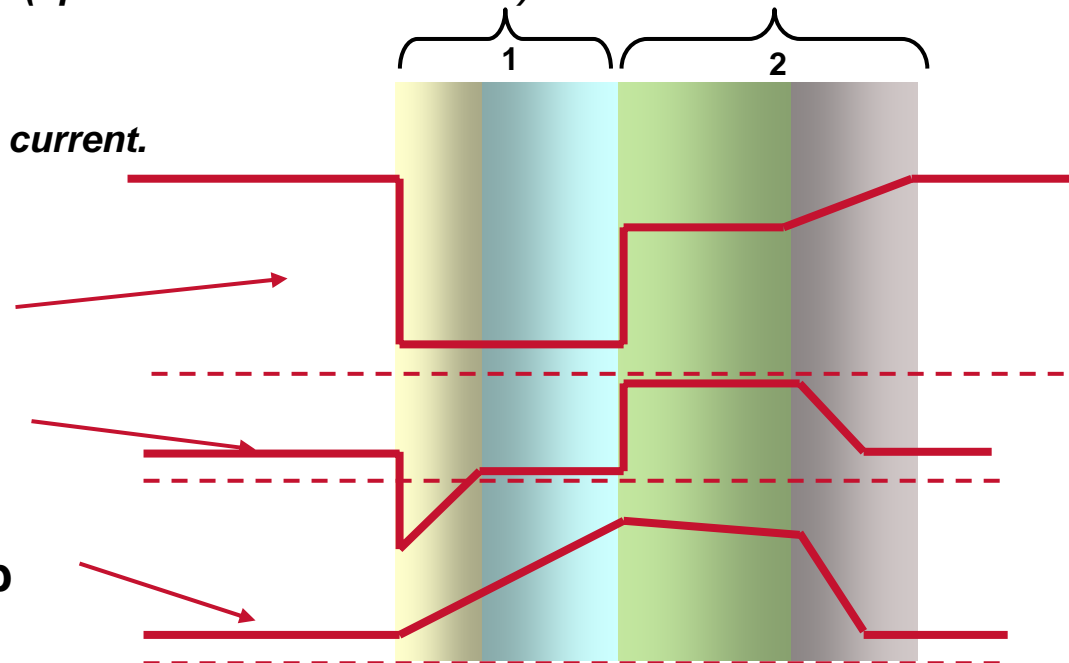
## ▶ Recovery phase (phase 2)

- High amount of reactive current.

◆ U network

◆ Iq Generator

◆ Speed or slip



# ***MAIN FACTORS ON SYSTEM BEHAVIOUR***

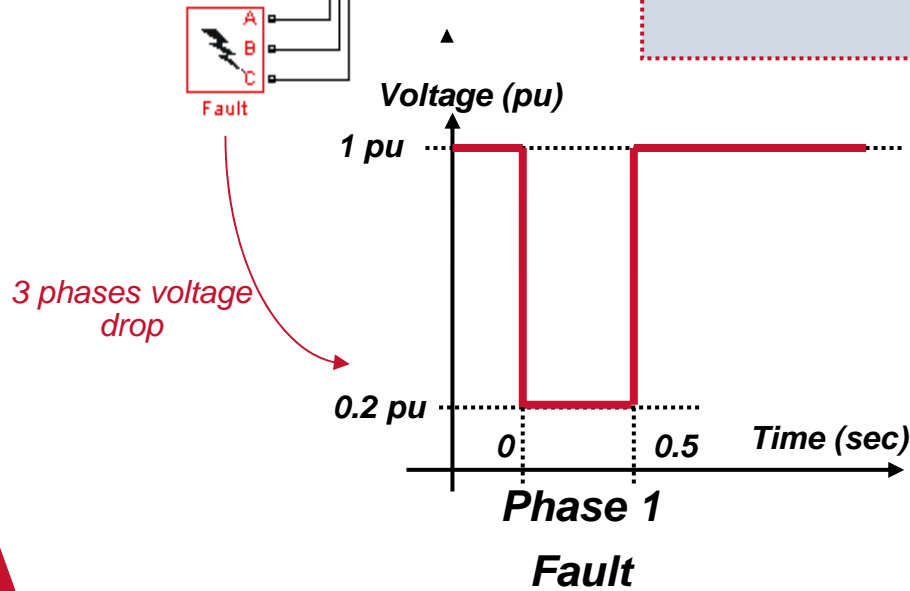
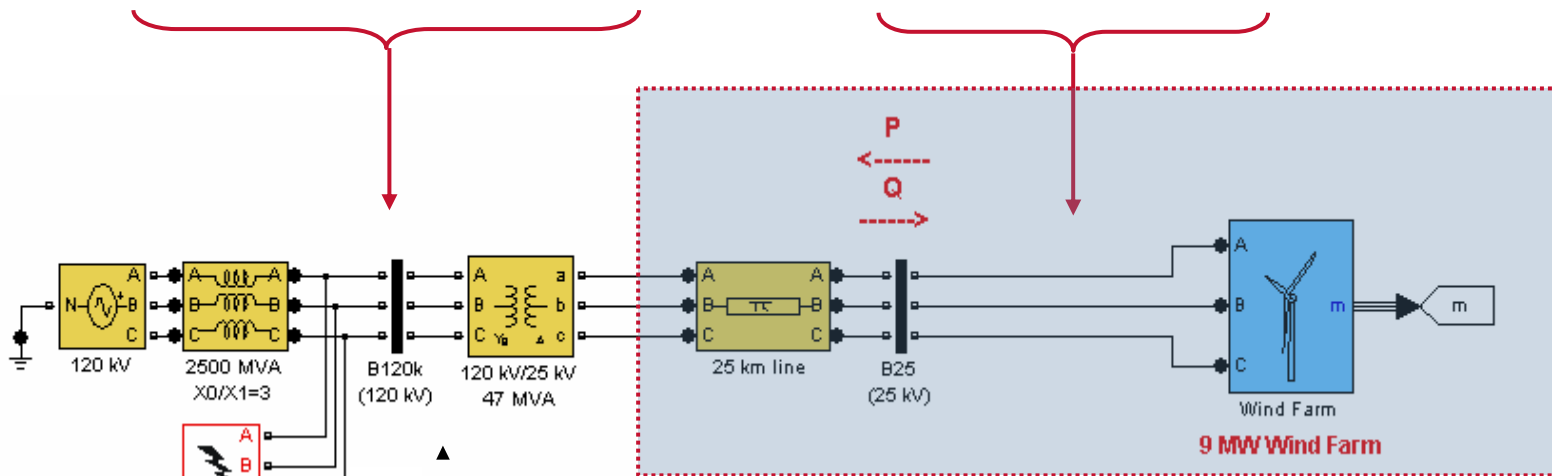


# MAIN FACTORS ON SYSTEM BEHAVIOUR GLOBAL VIEW

## ► 9MW Wind Farm Simulation

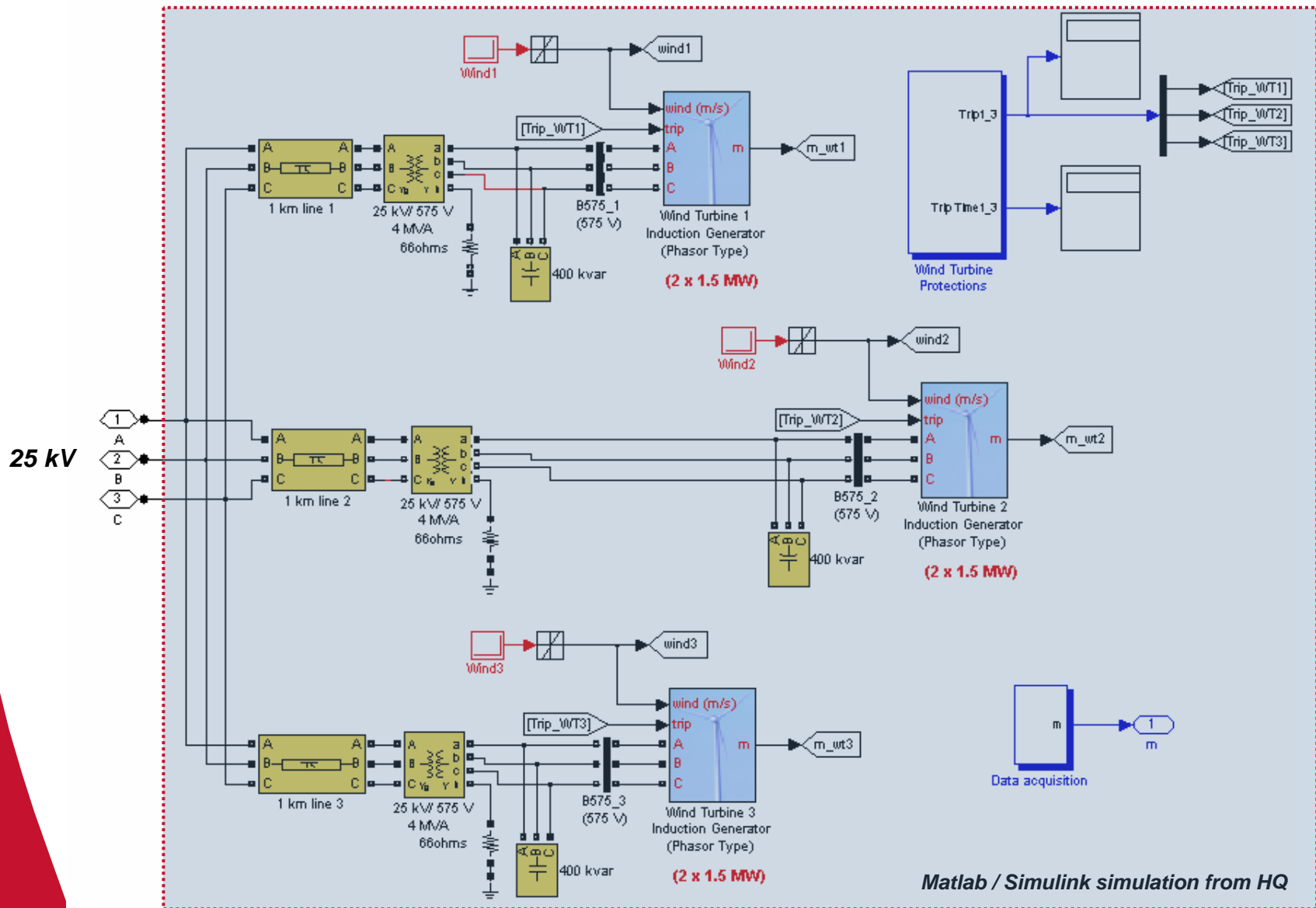
- Scc 2500MVA at 120kV Bus

- Scc 55MVA at 25kV Bus



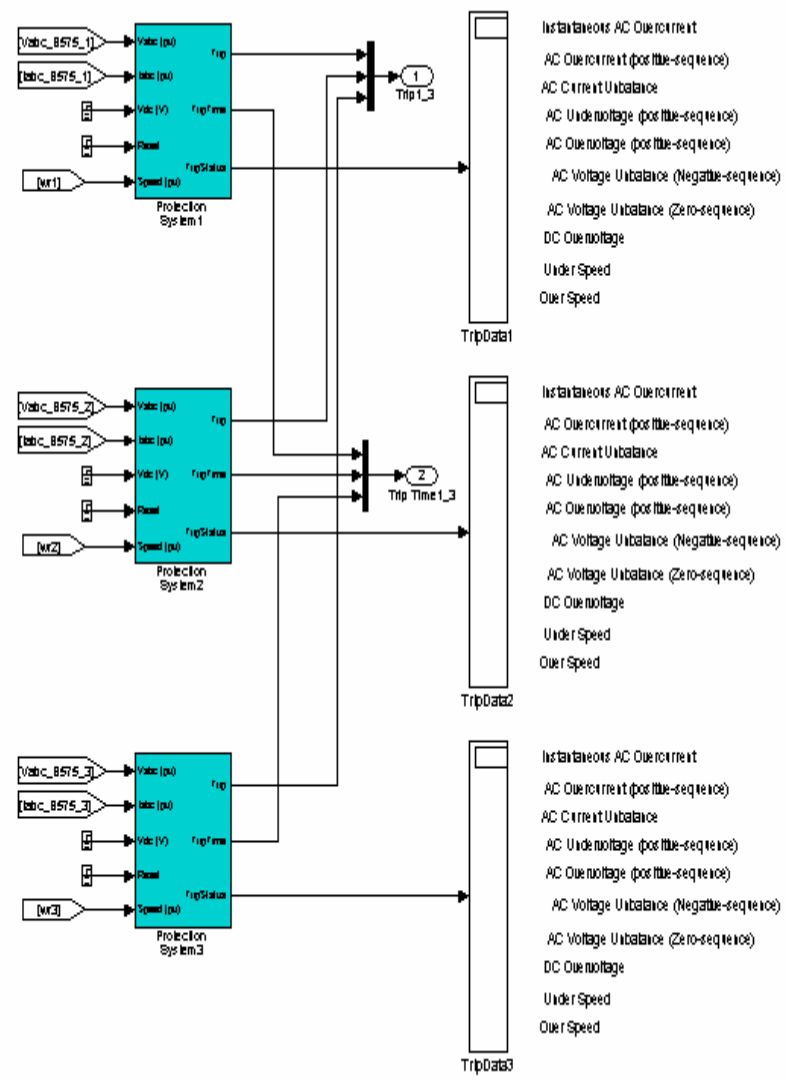
# MAIN FACTORS ON SYSTEM BEHAVIOUR

## GLOBAL VIEW- SIX WIND TURBINES



# MAIN FACTORS ON SYSTEM BEHAVIOUR SYSTEM PROTECTIONS

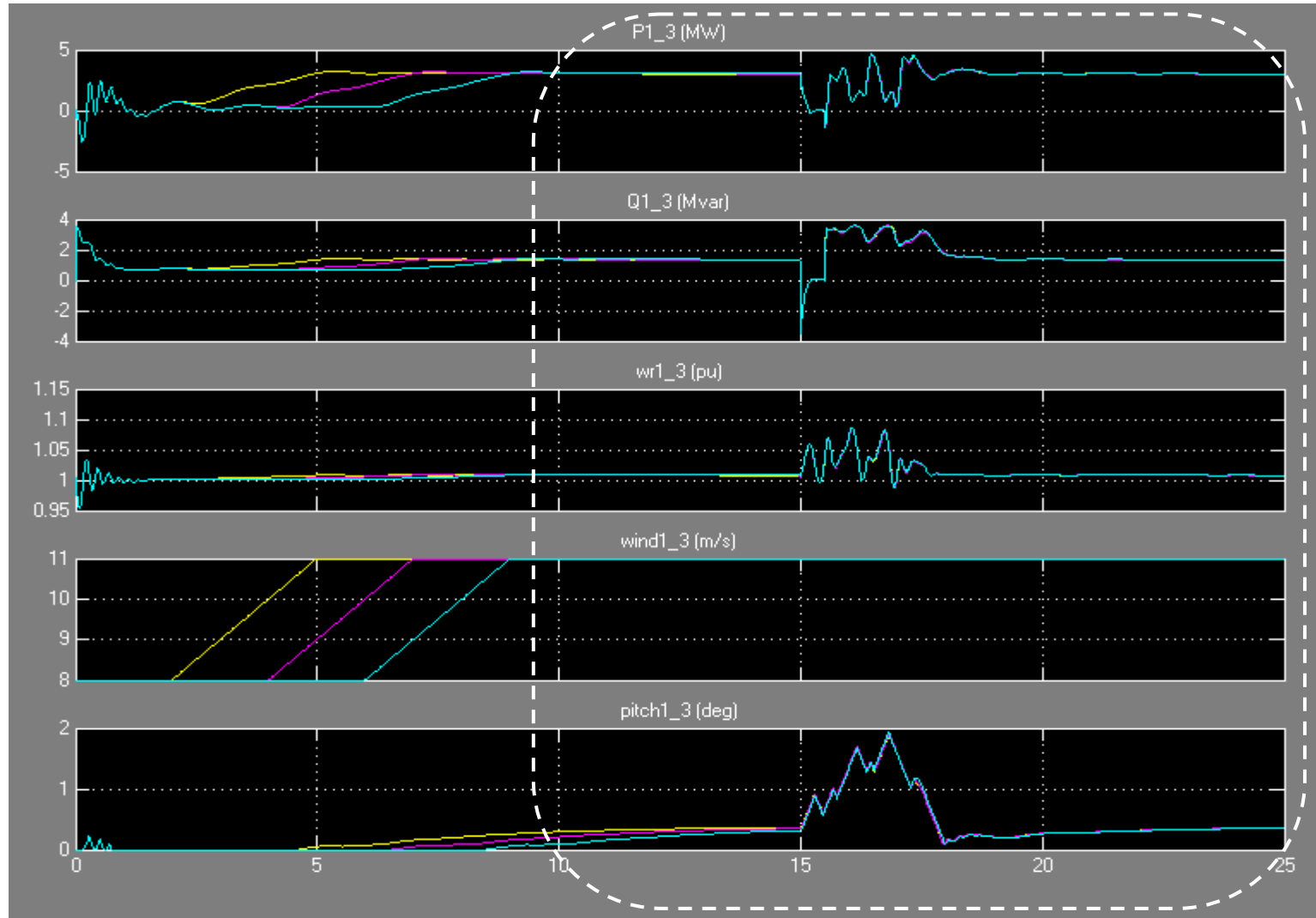
- ◆ **AC Overcurrent (Inst)**
- ◆ **AC overcurrent (positive seq.)**
- ◆ **AC current imbalance**
- ◆ **AC undervoltage (positive seq.)**
- ◆ **AC overvoltage (positive seq.)**
- ◆ **AC voltage unbalance (negative seq.)**
- ◆ **AC Voltage unbalance (Zero seq.)**
- ◆ **Underspeed**
- ◆ **Overspeed**



# Wind Farm Simulation *WITHOUT* compensation

## ▶ 9MW Wind Farm (With pitch control, pitch rate 2°/s)

◆ at wind turbine bus

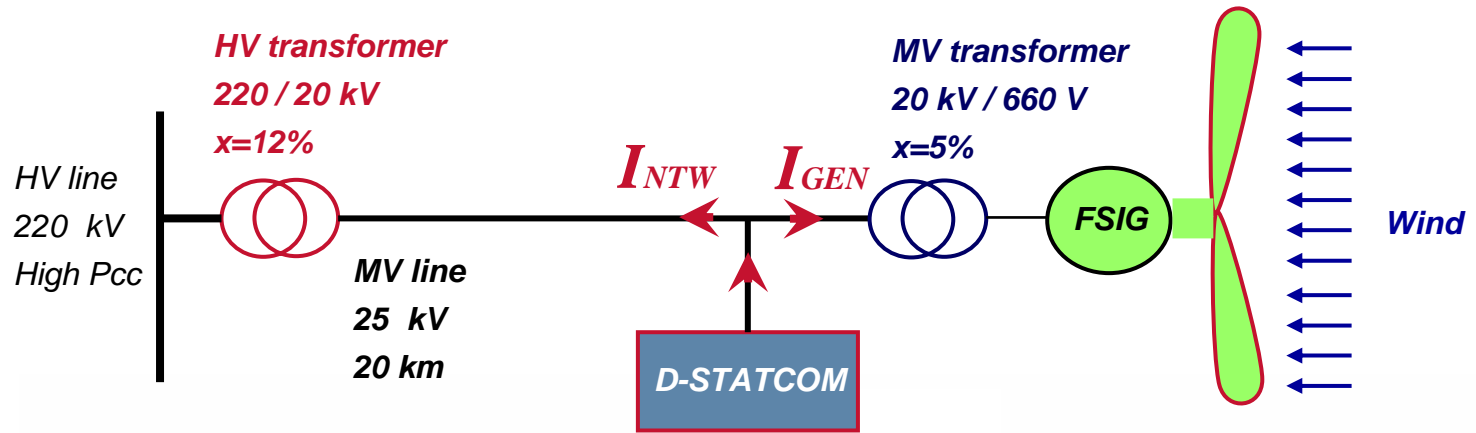


# WIND FARM SIMULATION WITHOUT COMPENSATION PITCH CONTROL - SYNTHESIS

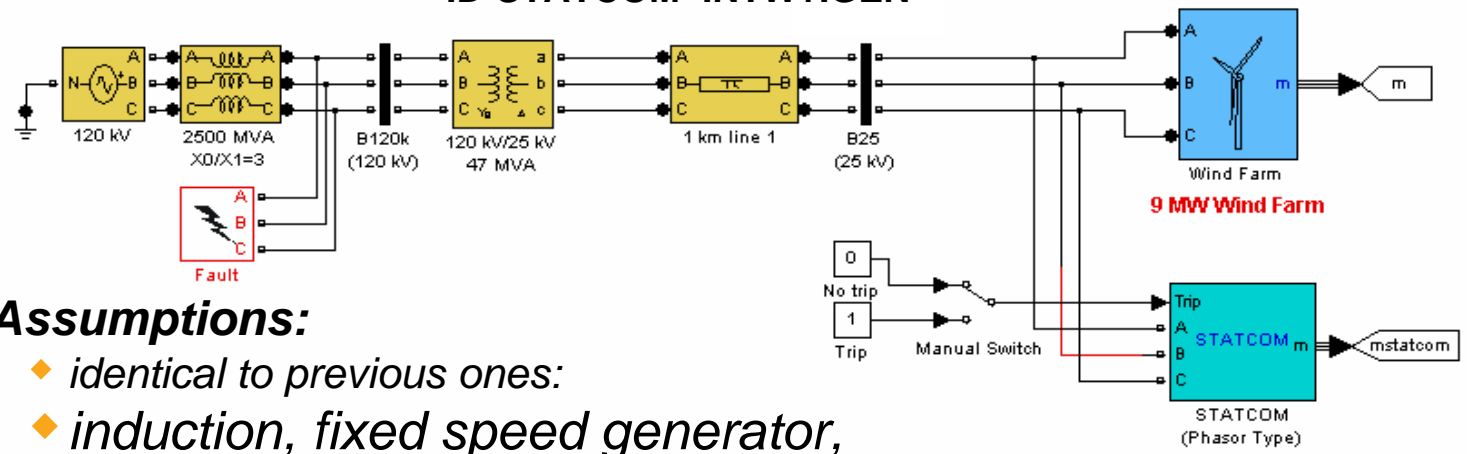
- ▶ **9MW Wind Farm (With pitch control, pitch rate 2°/s)**
  - ◆ **With taken assumptions**
    - **Fault duration 500ms**
    - **protection levels**
  - ◆ **Wind Farm won't trip with the help of pitch control DURING fault recovery**
  - ◆ **High reactive power consumption during fault recovery untill pulling in.**
  - ◆ **No respect of Fig 4.2 of P.O.12.3**

# 2 - WINDFARM OPERATION WITH COMPENSATION

# WITH COMPENSATION - SINGLE LINE DIAGRAM



$$ID-STATCOM = INTW + IGEN$$



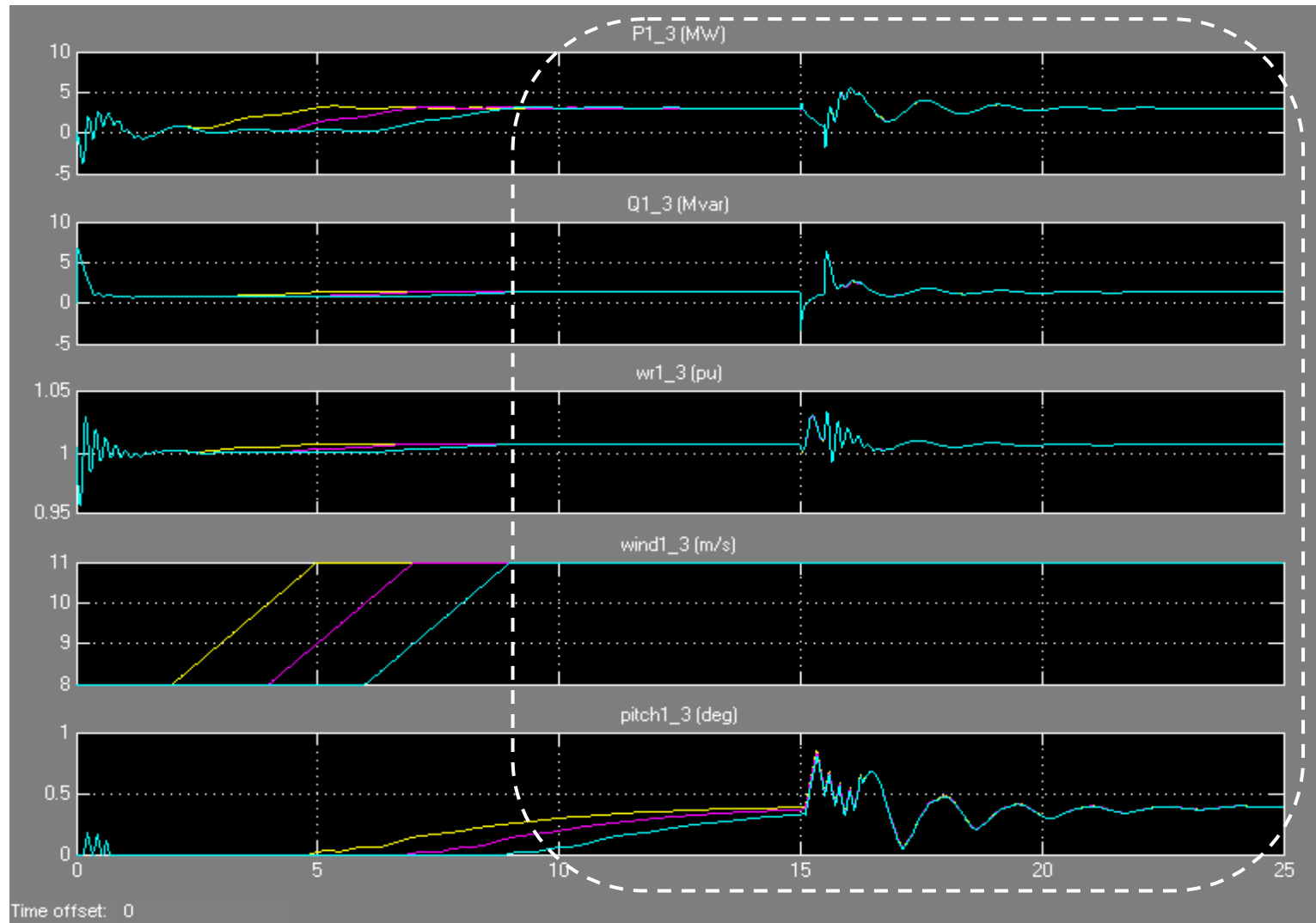
## Assumptions:

- ◆ identical to previous ones:
- ◆ induction, fixed speed generator,
  - in principal, network arrangement,
  - wind-farm power: from 30 to 50 MVA (approach in pu),
- ◆ in addition, D-STATCOM for compensation:
  - VSC equipment,
  - installed power in pu.

# Wind Farm Simulation With D-STATCOM

► **9MW Wind Farm (with pitch control pitch rate 2°/s)**

- ◆ at Wind turbine (D-STATCOM 19.5MVA ~2.16 p.u.)





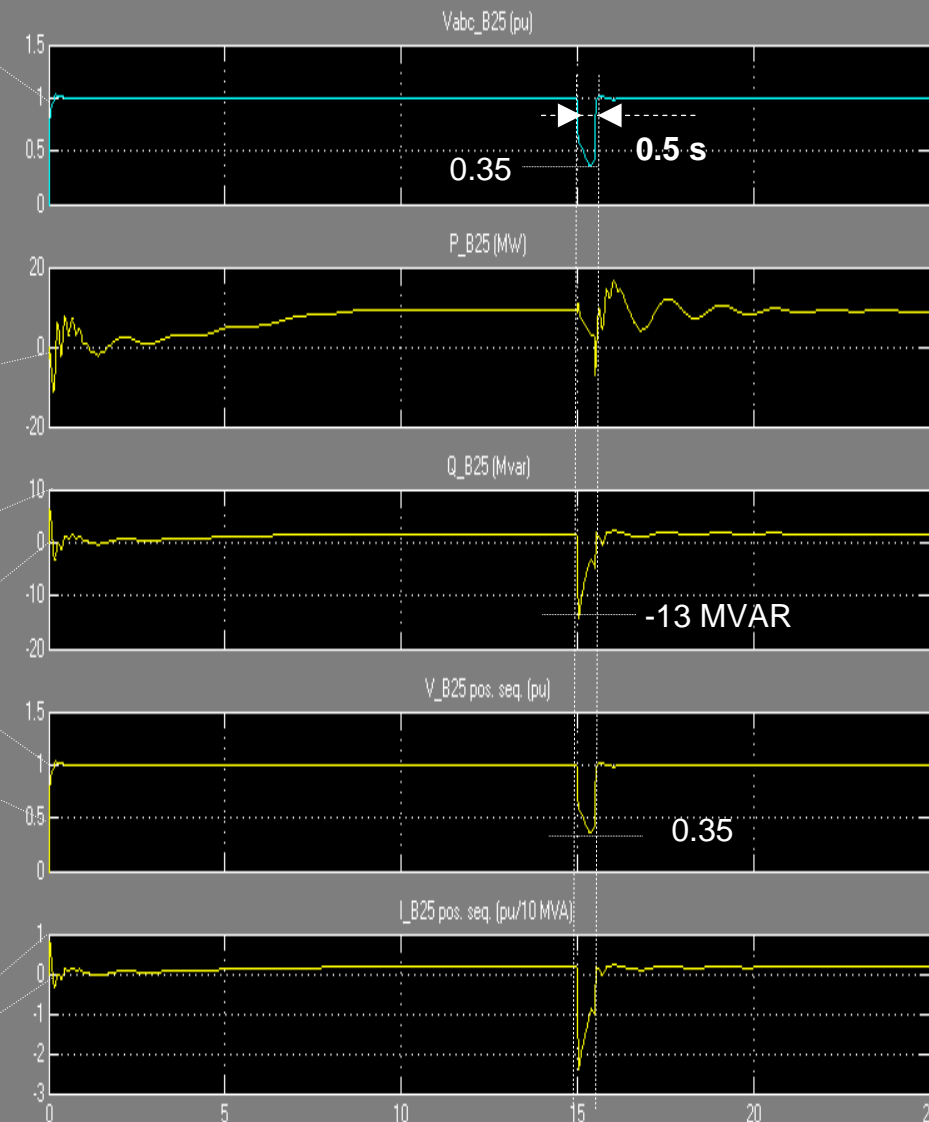
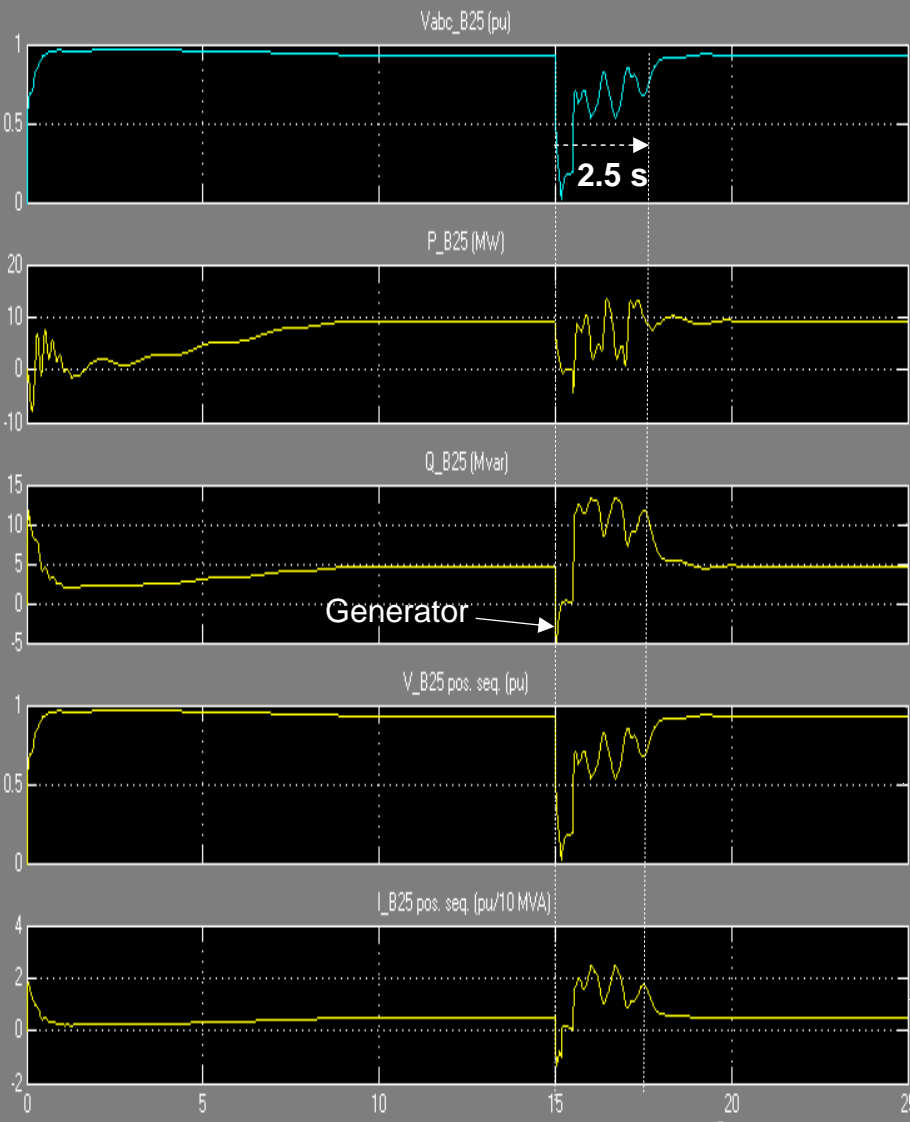
# WIND FARM SIMULATION WITH D-STATCOM

- ▶ **9MW Wind Farm (with pitch control pitch rate 2°/s)**
  - ◆ *With taken assumptions*
  - ◆ *With the help of 2.16 p.u of D-STATCOM,*
  - ◆ *No reactive power consumption during fault and after recovery*
  - ◆ *Respect of 1 p.u current injection at Pcc during fault*

# **3 - CONCLUSION & COST MITIGATION**

## Without dynamic compensation

## With 19.5 MVAR D-STATCOM



No respect of Fig 4.2 of P.O.12.3

Time offset: 0

# WIND FARM WITH COMPENSATION CONCLUSION

▶ **ASSUMPTION: Fixed Speed Induction generator case**

▶ **MAIN CONCLUSION:**

◆ **Case by Case study**

- **Network data**

- *Impedance of Connecting transformer and line*

- **Wind turbine data:**

- *type of active power and speed control*

- *design for protection levels*

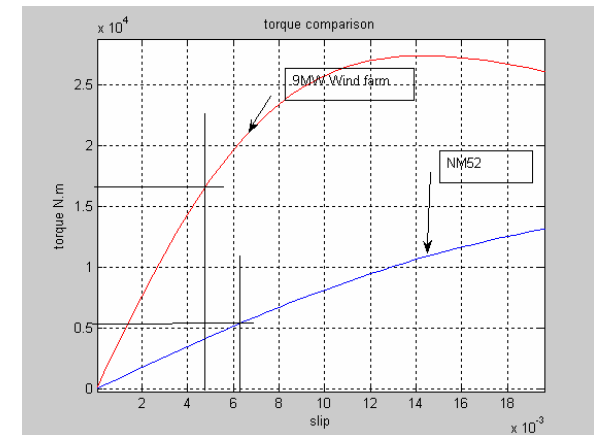
- *Inertia*

- **Generator data**

- *Curve Torque/slip*

- *ratio  $s_k/s_n$  and  $T_{ek}/T_{en}$*

◆ **Huge amount of reactive power needed during faults ...**

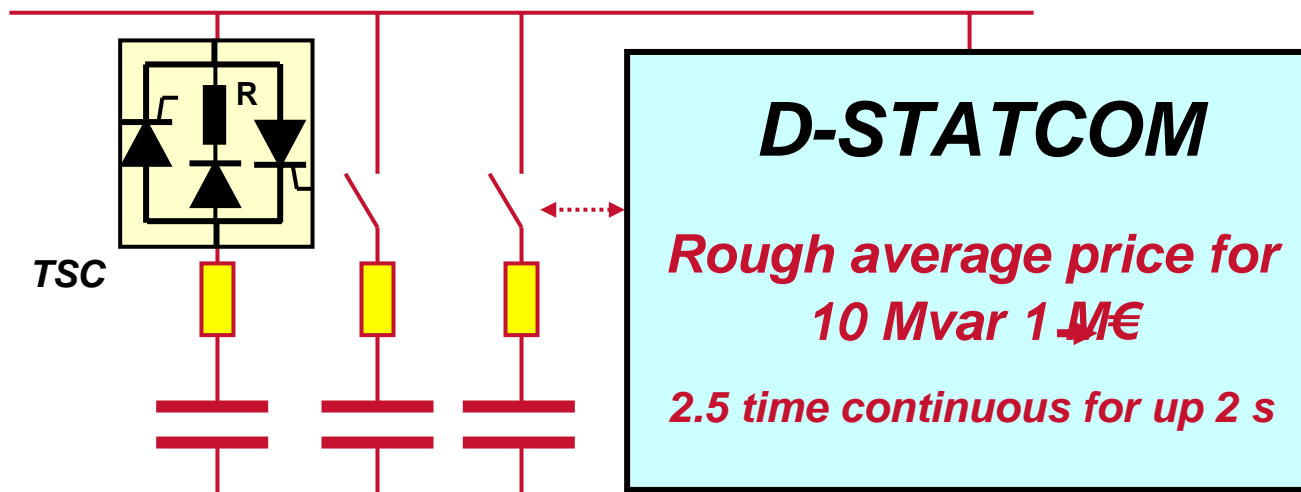


# WIND FARM WITH COMPENSATION COST MITIGATION

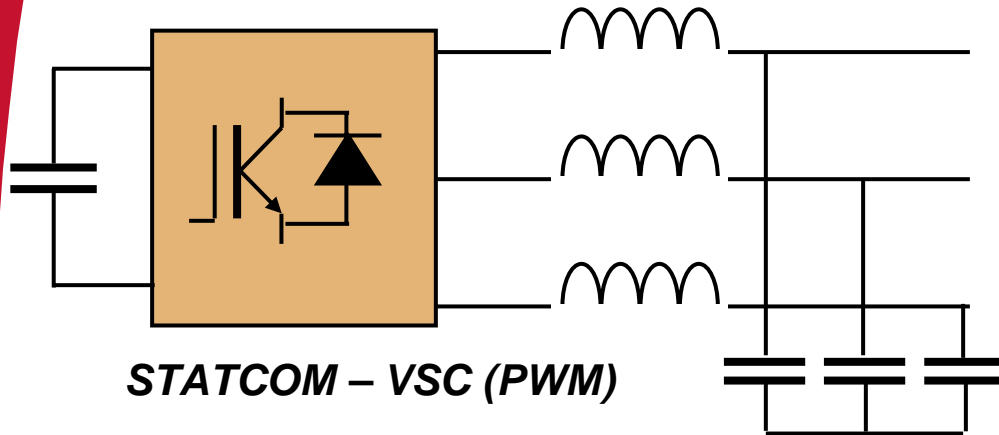
▶ **ASSUMPTION: Fixed Speed Induction generator case**

▶ **Costs mitigation**

- ◆ *Power electronics VSC has a typical overload capability of 2 - 2.3*
- ◆ *Keeping our case study: SVS size = 1.15 p.u with x 2 overload capability*
- ◆ *To reduce costs:*
  - *Splitting SVS in D-STATCOM and MSC*
  - *Splitting SVS in D-STATCOM and TSC.*
  - *.../...*



10 Mvar peak → 1 M€ .... EXPENSIVE....



STATCOM – VSC (PWM)

**BUT ... In normal operation the STATCOM ...**

- May control  $\cos \phi$
- May eliminate the negative sequence.
- Can be a active filter
- Can be a dynamic damper.

Just for  $\cos \phi$  and negative sequence, the simple SVC is a good solution.

